

Structured Prediction with Indirect Supervision

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Joint Work With James Clarke, Dan Goldwasser,
Lev Ratinov, Vivek Srikumar, and Dan Roth

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Semantic Parsing

INPUT

What is the largest state that borders New York and Maryland?

OUTPUT

```
largest( state( next_to( state(NY) ) AND next_to(state(MD))))
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A structured task: multiple interdependent decisions

- city(NY) or state(NY)?
- state(next_to(.)) \neq next_to(state(.))

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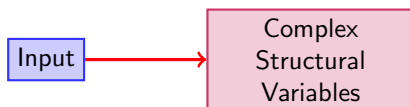
A structured task: multiple interdependent decisions

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- state(next_to(.)) \neq next_to(state(.))

Supervision cost

- Labeling data is **very expensive!**
- The annotators need to know how to write meaning representation

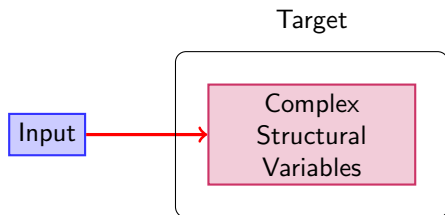
Main Idea: Indirect Supervision



Example

- Input Human Query, Output Meaning Representation

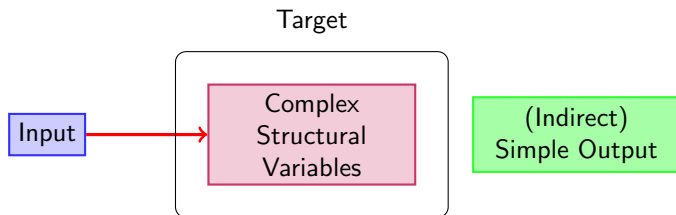
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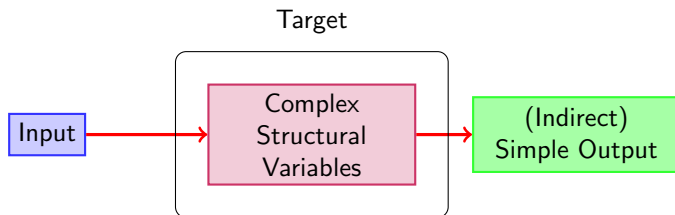
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- (Indirect) Simple Output : Is the answer correct?

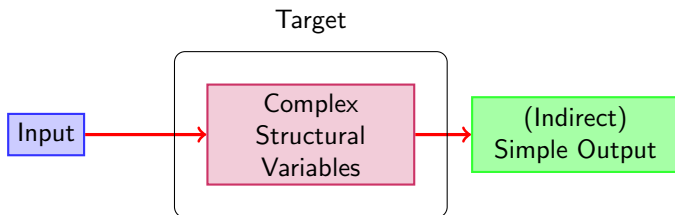
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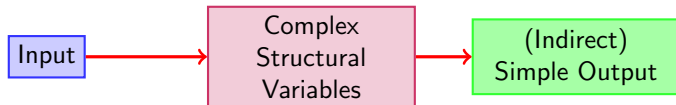
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Use indirect supervision signals

- Instead of supervising at the level of complex structures, use indirect supervision signals
- Indirect supervision signals are easier to obtain

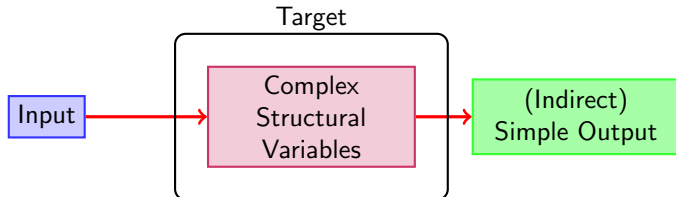
Part I: Learning with Latent Structure

Part II: Learning with Indirect Supervision

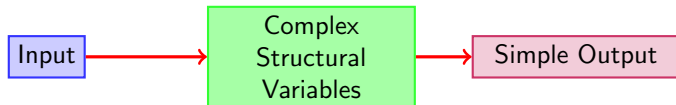


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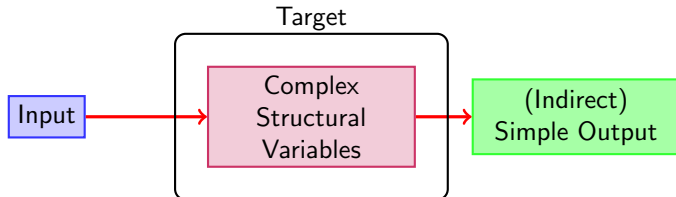
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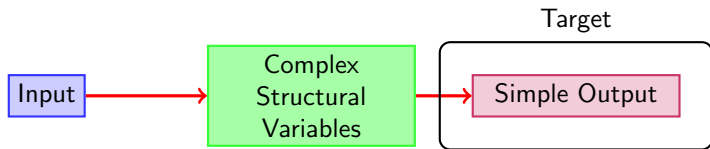
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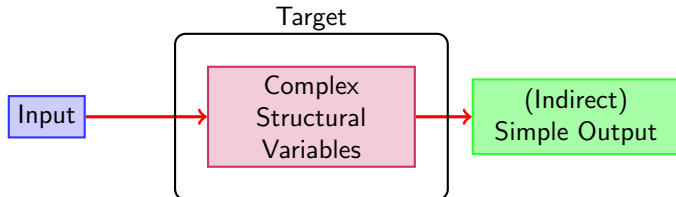
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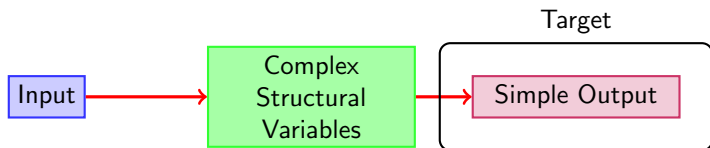
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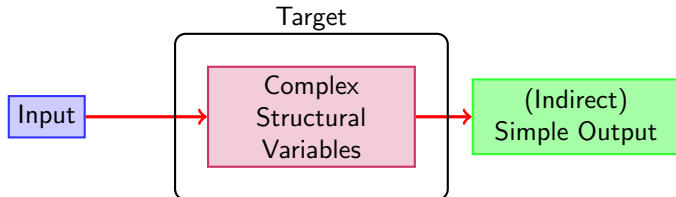
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Part II: Learning with Indirect Supervision



Example task: Paraphrase Identification

Yes/NO

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,
Bob
said

Bob
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- Q: Are sentence 1 and sentence 2 paraphrases of each other?

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Problem of interests

- Binary output problem: $z \in \{-1, 1\}$
- Intermediate representation: h
 - Some structure that justifies the positive label**
 - The intermediate representation is **latent** (not present in the data)

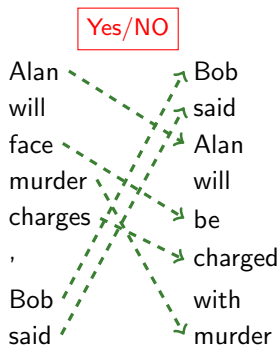
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intermediate representation $\Leftrightarrow \{1, -1\}$

- Only positive examples have good intermediate representations
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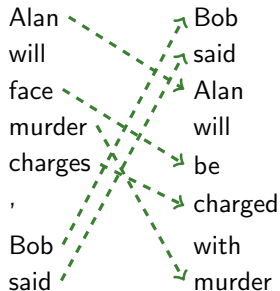
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- There must exist a good explanation that justifies the positive label
- $\exists \mathbf{h}, \mathbf{w}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$

- Pair \mathbf{x}_2 is negative

- No explanation is good enough to justify the positive label
- $\forall \mathbf{h}, \mathbf{w}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$

Geometric interpretation: the case of two examples

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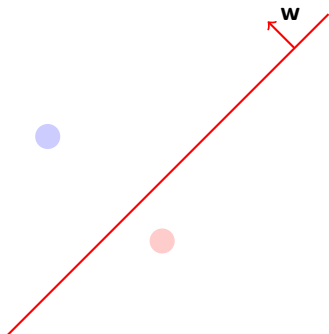
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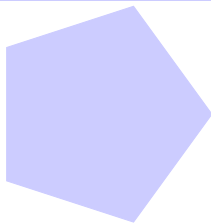
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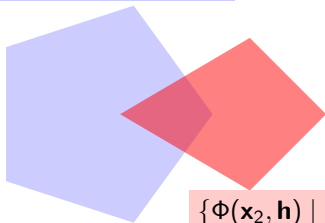
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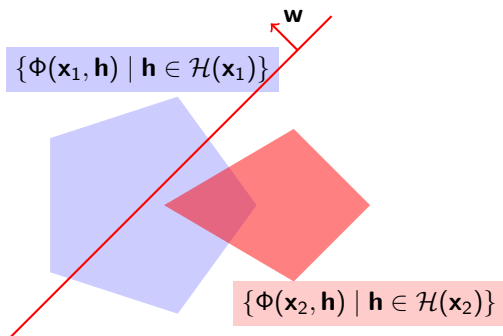
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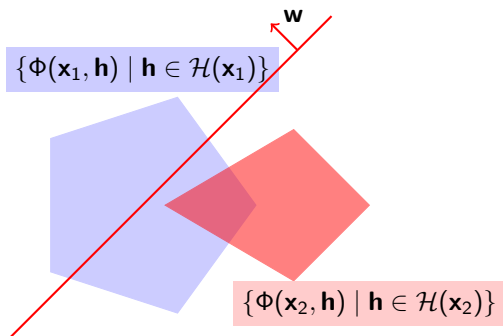
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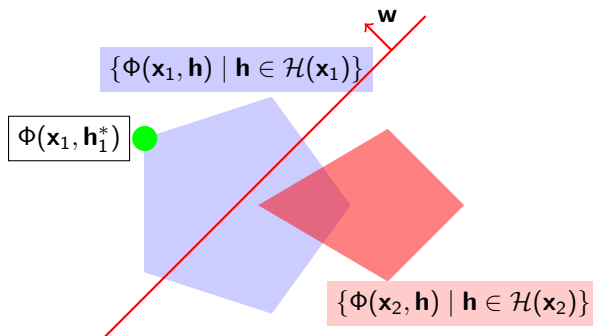
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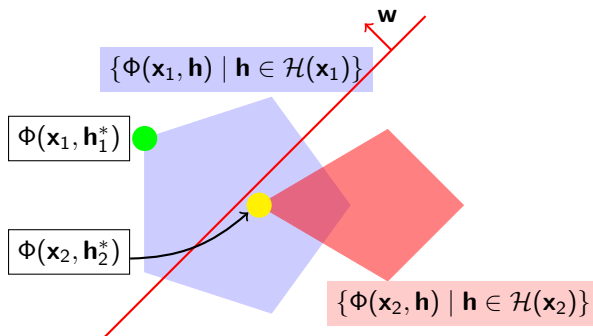
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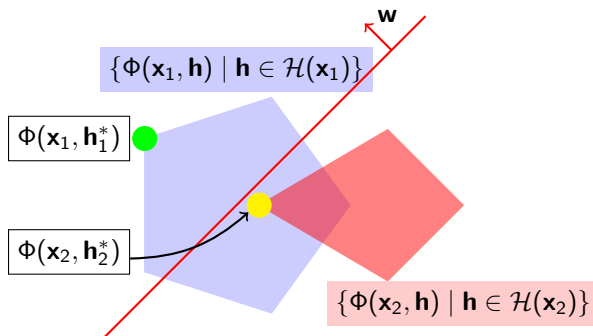


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- The prediction function:

$$\max_{\mathbf{h}} \mathbf{w}^T \Phi(\mathbf{x}, \mathbf{h})$$



Find Structures

- In the learning algorithm, we need to solve $\max_{\mathbf{h}} \mathbf{w}^T \Phi(\mathbf{x}, \mathbf{h})$
- A problem of assigning values to multiple interacting discrete variables

Constraint Based Declarative Framework

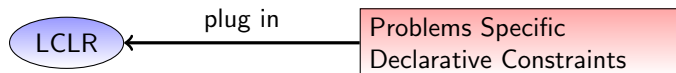
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 - ① Allow one to define the knowledge necessary for the problem declaratively
 - ② Avoid designing a special purpose inference algorithm for each problem.
- Final System: Learning Constrained Latent Representation (LCLR)

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Optimizing the objective function

$$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^l L_B(\mathbf{x}_i, y_i, \mathbf{w}) =$$
$$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^l \ell(-z_i \max_{\mathbf{h} \in \mathcal{H}} \mathbf{w}^T \sum_{s \in \Gamma(\mathbf{x})} h_s \Phi_s(\mathbf{x}))$$

- **Not a regular LR/SVM:** Inference procedures inside (pink boxed)
- **No shortcut** Calling a LR/SVM solver multiple times will not work
- Similar to MI-SVM and Latent-SVM

$$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^l L_{\mathcal{B}}(\mathbf{x}_i, y_i, \mathbf{w}) =$$
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Our solution

- A new optimization algorithm: Focus on square-hinge loss
 - EM-like procedure + Cutting plane methods + Dual coordinate descent
 - $\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{z_i=-1} L_{\mathcal{B}}(\mathbf{x}_i, y_i, \mathbf{w}) + C \sum_{z_i=+1} L_{\mathcal{B}}(\mathbf{x}_i, y_i, \mathbf{w})$
- Code available:
<http://cogcomp.cs.illinois.edu/page/software>

Tasks

- Transliteration: Is named entity B a transliteration of A?
- Textual Entailment: Can sentence A entail sentence B?
- Paraphrase Identification

Goal of experiments

- Determine if a joint approach be better than a two-stage approach?
- Joint approach also learns latent structures automatically

Two-stage approach versus LCLR

- Exactly **the same** features and definition of latent structures
 - Our two-stage approach uses a domain-dependent heuristic to find an intermediate representation
 - LCLR finds the intermediate representation automatically
- Initialization of LCLR: two-stage

Transliteration System	Joint	ILP	Acc	MRR
(Goldwasser and Roth 2008)	*		N/A	89.4
Our two-stage		*	80.0	85.7
Our LCLR	*	*	92.3	95.4

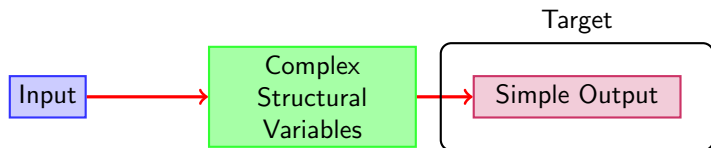
Entailment System	Joint	ILP	Acc
Median of TAC 2009 systems			61.5
Our two-stage		*	65.0
Our LCLR	*	*	66.8

Paraphrase System	Joint	ILP	Acc
<i>Experiments using (Dolan, Quirk, and Brockett 2004)</i>			
(Qiu, Kan, and Chua 2006)			72.00
(Das and Smith 2009)	*		73.86
(Wan, Dras, Dale, and Paris 2006)			75.60
Our two-stage		*	76.23
Our LCLR	*	*	76.41

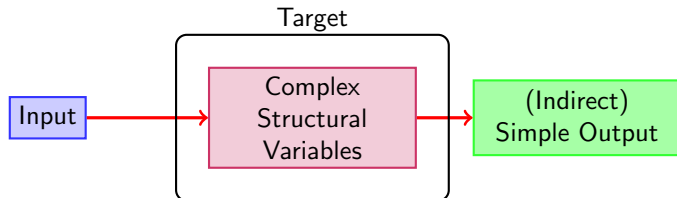
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<i>Experiments using Noisy data set</i>			
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Our LCLR	*	*	72.75

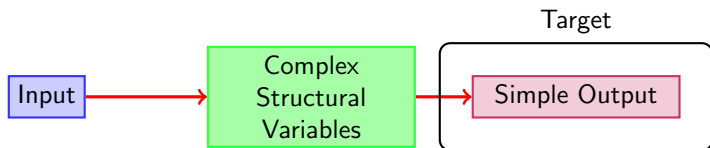
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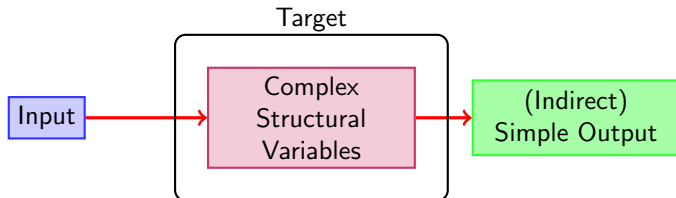
Part II: Learning with Indirect Supervision



Part I: Learning with Latent Structure



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Our Goal

- Given that supervising structures is time consuming and often requires expertise, our goal is to reduce the supervision effort for structured output learning.
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Research Question

Is it possible to use (and gain from) **additional cheap** sources of supervision?

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Given a car image, where are the body, windows and wheels?



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OUTPUT: **h**

Author

Author

Author

Author

Title

Title

INPUT: **x**

Lars

Ole

Andersen

.

Program

...



Task

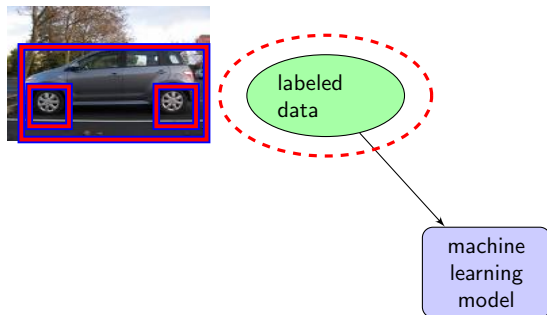
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Supervising structured output problems

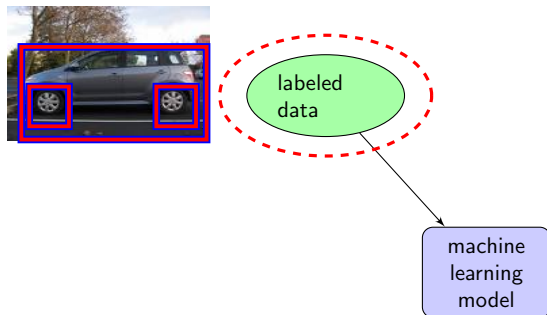


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- Supervised Approach

Supervising structured output problems

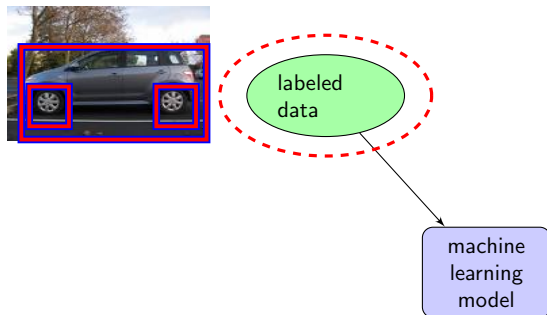


Task

Given a car image, where are the body, windows and wheels?

- Supervised Approach is **Expensive!**

Supervising structured output problems

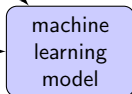
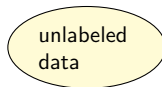
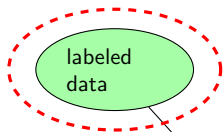


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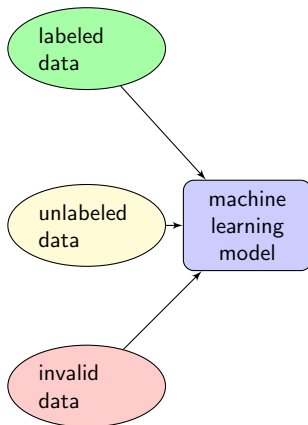


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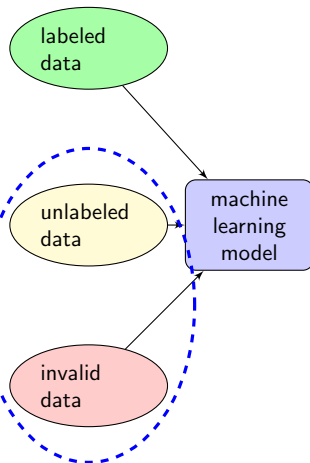


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Supervising structured output problems

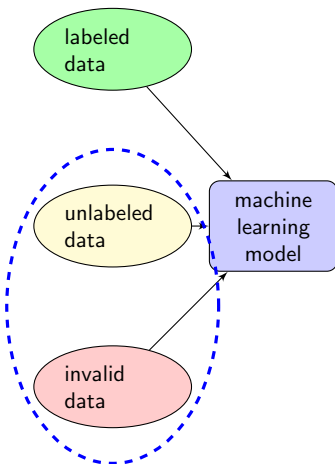


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Supervising structured output problems



Task

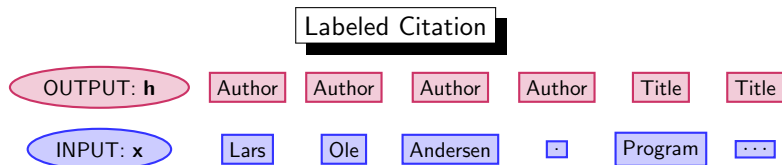
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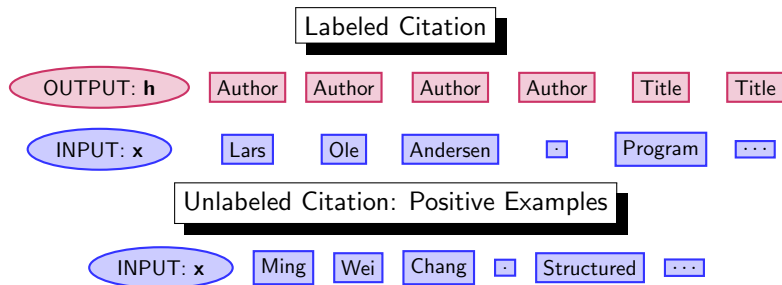
Indirect Supervision

Use binary labeled data as indirect supervisions

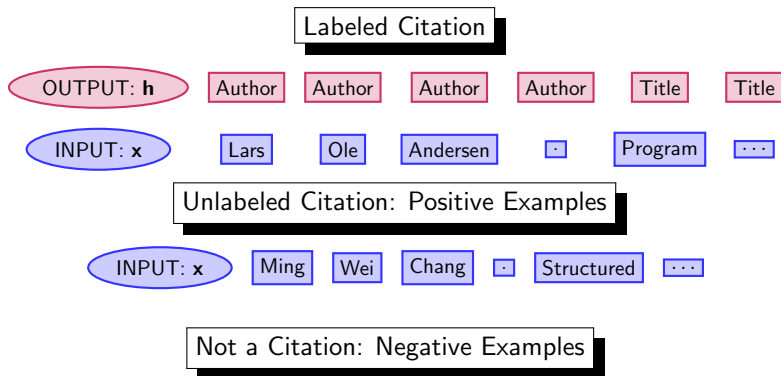
Supervised Learning algorithms



Semi-Supervised Learning algorithms



Indirect Supervision algorithm



- Shuffling tokens of a citation entry

Structured Output Task

Structured Output Task

Companion Binary Task

Structured Output Task

Companion Binary Task

Observation

Many structured output prediction problems have a **companion** binary decision problem: predicting whether an input possesses a good structure or not.

Structured Output Task

Companion Binary Task

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Why is this important

Binary labeled data is very easy to obtain

How to exploit it???

Structured Output Task

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Many structured output prediction problems have a **companion** binary decision problem: predicting whether an input possesses a good structure or not.

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The role of binary labeled data

Structured Output Learning

- Recognize Car parts



Companion Binary Output Problem

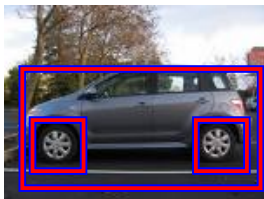
- Is there a car in this image?



The role of binary labeled data

Structured Output Learning

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Companion Task: Does this example possess a good structure?

Structured Output Learning

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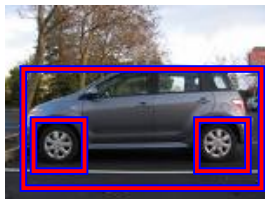


Companion Task: Does this example possess a good structure?

- x_1 is positive .
 - There must exist a good structure that justifies the positive label
 - $\exists \mathbf{h}, \mathbf{w}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$

Structured Output Learning

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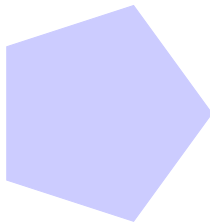
- x_1 is positive .
 - There must exist a good structure that justifies the positive label
 - $\exists \mathbf{h}, \mathbf{w}^T \Phi(\mathbf{x}_1, \mathbf{h}) \geq 0$
- x_2 is negative .
 - No structure is good enough. $\forall \mathbf{h}, \mathbf{w}^T \Phi(\mathbf{x}_2, \mathbf{h}) \leq 0$

Why is binary labeled data useful?

- \mathbf{x}_1 is positive : There exists a good structure
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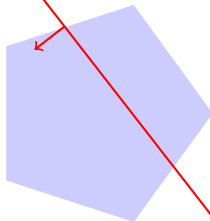


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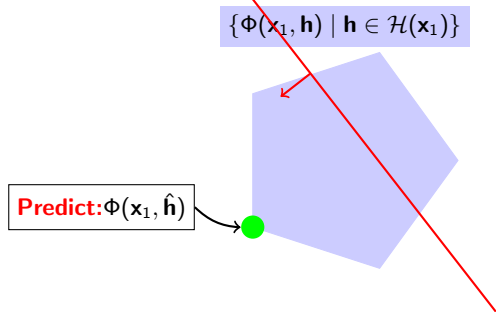
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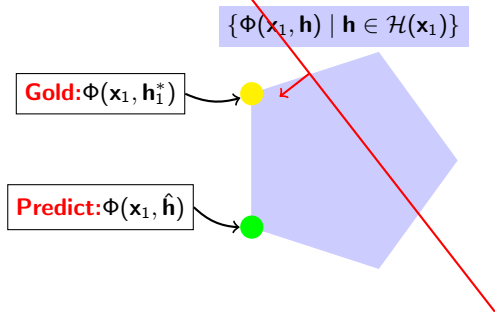
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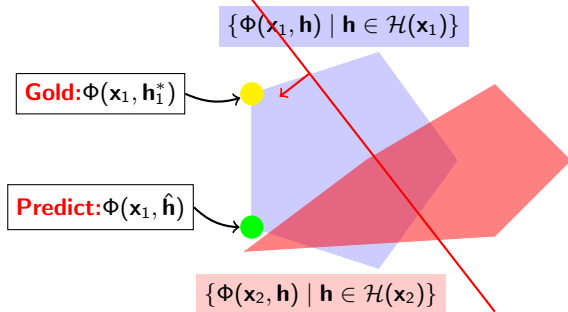
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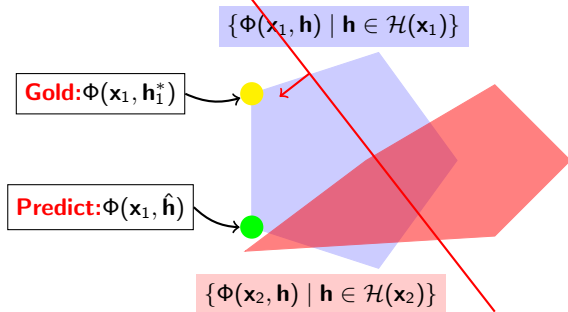
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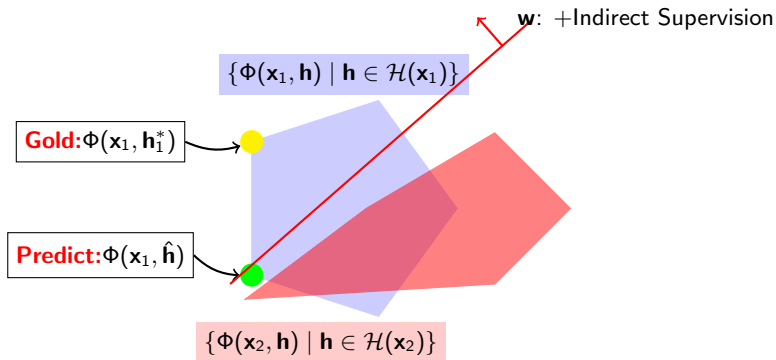
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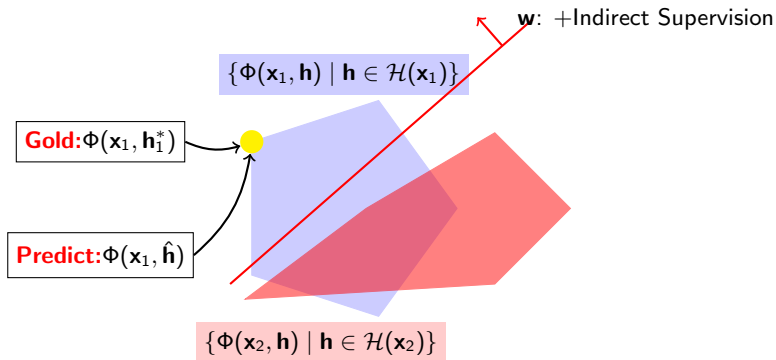
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$$\min_{\mathbf{w}} \frac{\|\mathbf{w}\|^2}{2} + C_1 \sum_{i \in S} L_S(\mathbf{x}_i, \mathbf{h}_i, \mathbf{w}) + C_2 \sum_{i \in B} L_B(\mathbf{x}_i, z_i, \mathbf{w}),$$

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- **Direct Supervision** : structured labeled data $S = \{(\mathbf{x}, \mathbf{h})\}$
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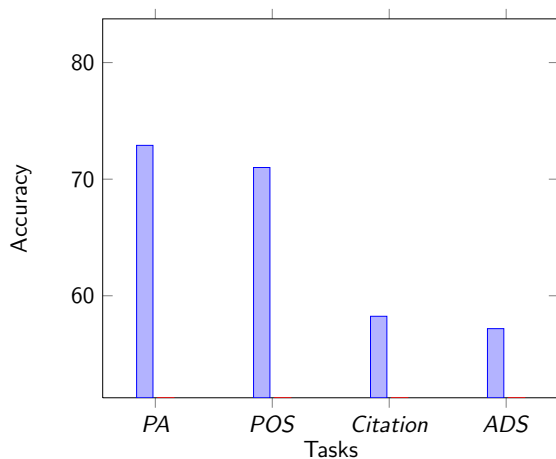
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Support Structured SVM

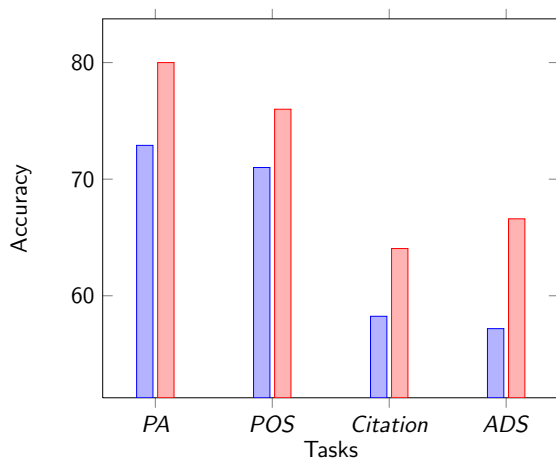
Experimental Results



- PA :
Phonetic Alignment
- ADS :
Advertisement field recognition

Structural SVM Joint Learning with Indirect Supervision

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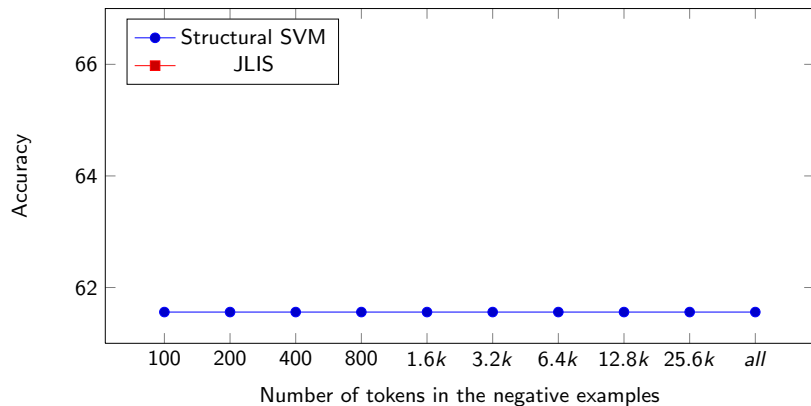
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- J-LIS: takes advantage of *both* positively and negatively labeled data

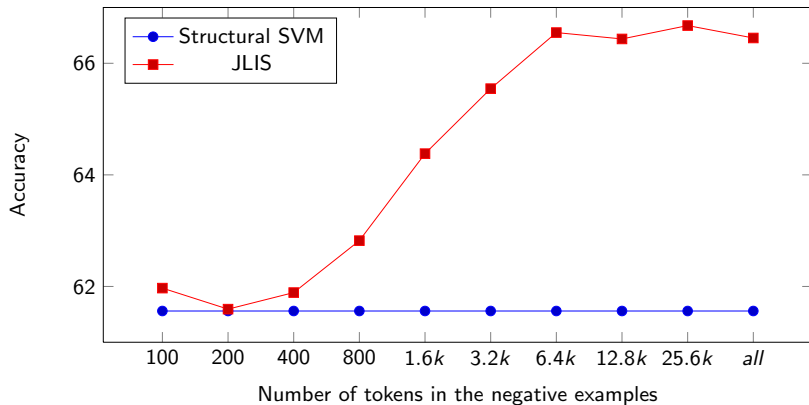
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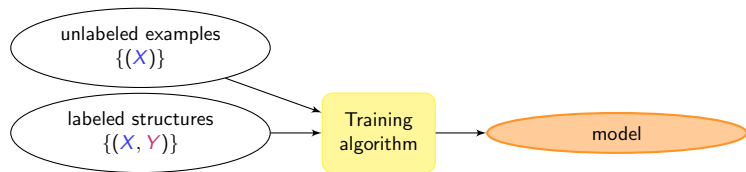


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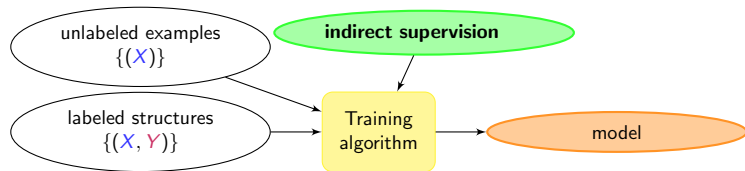
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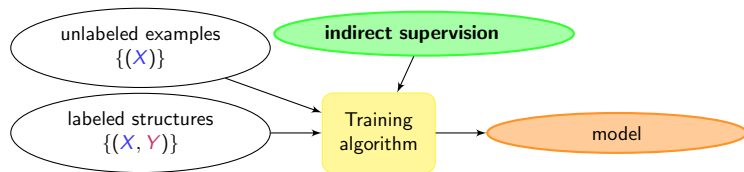


Recent publications about indirect supervisions



Recent publications about indirect supervisions





User Response as Indirect Supervisions

- Application: Mapping natural language into logical forms
- (Clarke, Goldwasser, Chang, and Roth 2010; Liang, Jordan, and Klein 2011)

Constraints as Indirect Supervisions

- Applications: Word Alignment, Dependency Parsing, Information Extraction
- (Chang, Ratnov, and Roth 2007; Mann and McCallum 2008; Ganchev, Graça, Gillenwater, and Taskar 2010; Carlson, Betteridge, Wang, Jr., and Mitchell 2010)

Target: Binary Output Variables

- We can find intermediate representations that help the binary decisions the most!
- Use Integer Linear Programming: Easy to apply to a new task

Target: Complex Structural Variables

- We can invent easy output problems to supervise the model
- We have a framework that can accept both direct and indirect supervision signals
- The use of negative examples is important

General Indirect Supervision

- It is possible to invent new indirect supervision signals
- It has been shown to be useful in many applications

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Thank you!

I t a l y

איטליה

I t a l y

איטליה

Structured Output Learning

Given one English NE and its Hebrew transliteration, tell me what are the phonetic alignments?

Example: Transliteration



Structured Output Learning

Given one English NE and its Hebrew transliteration, tell me what are the phonetic alignments?

Example: Transliteration

Italy
איטליה



Israel
אילינוי

Structured Output Learning

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Italy
איטליה

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Yes/No
אילינוי

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Given one English NE and its Hebrew transliteration, tell me what are the phonetic alignments?

Companion Binary Output Problem

Are these two NEs a transliteration pair?

Example: Transliteration

Italy
איטליה

Israel
Yes/No
אילינוי

Structured Output Learning

Given one English NE and its Hebrew transliteration, tell me what are the phonetic alignments?

Companion Binary Output Problem

Are these two NEs a transliteration pair?

Is there any connection between these two problems?

Italy
איטליה

Israel
Yes/No
אילינוי

Structured Output Learning


Given one English NE and its Hebrew transliteration, tell me what are the phonetic alignments?

Companion Binary Output Problem

Are these two NEs a transliteration pair?

Relationships

- Only a transliteration pair can have good phonetic alignment!
- Non-transliteration pairs cannot have good phonetic alignment!

-  Carlson, A., J. Betteridge, R. C. Wang, E. R. H. Jr., and T. M. Mitchell (2010).
Coupled semi-supervised learning for information extraction.
In Proceedings of the Third ACM International Conference on Web Search and Data Mining.
-  Chang, M., L. Ratinov, and D. Roth (2007).
Guiding semi-supervision with constraint-driven learning.
In ACL.
-  Clarke, J., D. Goldwasser, M. Chang, and D. Roth (2010).
Driving semantic parsing from the world's response.
In Proceedings of the Fourteenth Conference on Computational Natural Language Learning (CoNLL-2010).
-  Das, D. and N. A. Smith (2009).
Paraphrase identification as probabilistic quasi-synchronous recognition.
In ACL.
-  Dolan, W., C. Quirk, and C. Brockett (2004).
Unsupervised construction of large paraphrase corpora: Exploiting
massively parallel news sources

In *COLING*.



Ganchev, K., J. Graça, J. Gillenwater, and B. Taskar (2010).
Posterior regularization for structured latent variable models.
Journal of Machine Learning Research.



Goldwasser, D. and D. Roth (2008).
Active sample selection for named entity transliteration.
In *ACL*.
Short Paper.



Liang, P., M. I. Jordan, and D. Klein (2011).
Learning dependency-based compositional semantics.
In *ACL*.



Mann, G. and A. McCallum (2008).
Generalized expectation criteria for semi-supervised learning of
conditional random fields.
In *ACL*.



Qiu, L., M.-Y. Kan, and T.-S. Chua (2006).
Paraphrase recognition via dissimilarity significance classification.
In *EMNLP*.



...

A linear programming formulation for global inference in natural language tasks.

In H. T. Ng and E. Riloff (Eds.), *CoNLL*.



Wan, S., M. Dras, R. Dale, and C. Paris (2006).

Using dependency-based features to take the para-farceöut of paraphrase.

In *Proc. of the Australasian Language Technology Workshop (ALTW)*.